

# Some Properties of the Covariant Functor Set of Exponential Type

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## Abstract

In this paper, it is shown that the sets of all non-empty subsets Set(X) of a topological space X with exponential topology is a covariant functor in the category of Top-topological spaces and their continuous mappings into itself.

It is shown that the functor Set is a covariant functor in the category of topological spaces and continuous mappings into itself, a pseudometric in the space Set(X) is defined, and compact, connected, finite, and countable subspaces of Set(X) are distinguished. It also shows various kinds of connectivity, soft, locally soft, and n-soft mappings in Set(X). One interesting example is given for the  $TOP_Y$  category. It is proved that the functor Set maps open mappings to open, contractible and locally contractible spaces and into contractible and locally contractible spaces. Next, we study the problem of the propagation of mappings in the space Set(X) and distinguish which sets the basic open sets of the space Set(X) consist of. The following takes place:

a) The Set functor is a covariant functor in the Top category;

b) The functor  $\operatorname{Set}: Top \to Top$  preserves the layers of a continuous mapping, that is,  $(\operatorname{Set}(f))^{-1}(f(A)) = \operatorname{Set}(f^{-1}(A)).$ 

c) The functor Set preserves the contractibility of topological spaces.

**Key-words:** Functors, Mappings, Connection, Soft Mappings, Contractility, Homotopy, Absolute Extensors.

#### 1. Introduction

Let X be a topological space. Let Set(X) denote the family of all nonempty subsets of it, that is,  $Set(X) = \{F : F \subset X, F \neq \emptyset\}$ . Let  $\gamma = \{F_1, F_2, F_3, ..., F_s\}$  be a finite family of nonempty open subsets of the space X, that is,  $\gamma = \{F_1, F_2, F_3, ..., F_s\}$ , where  $F_i \neq 0$  and  $F_i$  is open in X. Consider a set of the form:

$$O_{\gamma}(F_1, F_2, ..., F_s) = \{A : A \subset \bigcup_{i=1}^s F_i \text{ and } A \cap F_i \neq \emptyset \text{ for } i = \overline{1, s} \}.$$

The families of all sets of this kind are  $O(F_1, F_2, ..., F_s)$ , i.e.  $B = \{O(F_1, F_2, ..., F_s) : F_i - is$ open in X and non-empty form, by definition, the base of the exponential topology Vietoris of the Set X.

If X is a metric space with metric  $\rho$ , then, following Hausdorff, it is natural to introduce the pseudometrics  $\rho'_{H}$  on the family Set(X) using the formula:

$$\rho'_H(A,B) = \max\{\sup_{a\in A} \rho(a,B), \sup_{b\in B} \rho(b,A)\},\$$

those. a topological space with this  $\rho'_H$  Hausdorff pseudometric is a  $(\text{Set}(X), \rho'_H)$  pseudo-metric space.

Recall that a mapping  $\rho(x, y): X \times X \to R_+$  is called pseudometric on a set X if  $\rho(x, y)$  satisfies the following conditions:

- P1.  $\rho(x, x) = 0$  for any X;
- P2.  $\rho(x, y) = \rho(y, x)$  for any  $x \in X$ ,  $y \in X$ ;
- P3.  $\rho(x, y) + \rho(y, z) \ge \rho(x, z)$  for any  $x, y, z \in X$ .

If we consider the family  $\exp X = \{F : F \subseteq X, F - \text{ is closed in } X\}$  of all non-empty closed subsets of the space X. This  $\rho'_H$  Hausdorff pseudo-metric will be the metric on expX. Obviously,  $\exp X$  is a subspace of  $\operatorname{Set}(X)$ .

Consider a mapping  $i: X \to Set(X)$  assigning to each point x a set i(X) consisting of exactly this one point x, i.e.  $i(x) = \{x\} \in Set(X)$ . For this, the mapping i satisfies the equality

$$i^{-1}(O(F_1, F_2, ..., F_k)) = \bigcap_{i=1}^k F_i.$$
(1)

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This means that the mapping i is continuous. For a family  $\gamma$  consisting of one set  $\Gamma$ , we obtain from this that  $i(\Gamma) = O(\Gamma) \bigcap X$ . Hence, i-open mapping. Since it is one-to-one, by virtue of equality (1) it will be a topological embedding of the space X into the space Set(X). Hence, for any topological space X, we can assume that X-topologically lies in Set(X).

Thus, for any topological space X, a topological space Set(X) is defined, which topologically contains the given space X as a subset.

Each mapping  $f: X \to Y$  can be considered as follows  $f: X \to Y \to \text{Set}Y$ . Hence, each mapping  $f: X \to \text{Set}(Y)$  will be denoted by  $\text{Set}(f): \text{Set}(X) \to \text{Set}(Y)$  or, in short, by the Set(f)-mapping defined by the formula:

 $(\operatorname{Set} f)(A) = \bigcup \{ f(a) : a \in A \}$  for each  $A \in \operatorname{Set}(X)$ .

The following takes place

Lemma 1 [1]. If  $f: X \to Y$  is a continuous mapping between topological spaces X and Y, , then  $Set(f): Set(X) \to Set(Y)$  is a continuous mapping between Set(X) and Set(Y).

In this case, for any continuous mapping  $f: X \rightarrow Y$ , the following diagram holds

$$\begin{array}{ccc} X & \stackrel{f}{\longrightarrow} Y \\ & \downarrow i_{X} & \downarrow i_{Y} \end{array} \tag{2}$$
$$\operatorname{Set}(X) \xrightarrow{\operatorname{Set}(f)} \operatorname{Set}(Y) \end{array}$$

Let X be a topological space. We denote by  $\exp X = \{F : \overline{F} = F, F \subseteq X, F \neq \emptyset\}$  the family of all nonempty closed subsets of it;

 $\exp^{c}(X) = \{F : F - \text{ is compact}; F \subseteq X\}$  is the family of all compact subsets;

 $\exp^{con}(X) = \{F: F - \text{ is connected}, F \subseteq X\}$  is the family of all connected subsets;

 $\exp^{ccon}(X) = \{F : F - \text{ is connected and } F - \text{ is compact } F \subseteq X\}$  is the family of all connected compact subsets of X.

Each of these families will be considered by the aforementioned Vystoris exponential topology.

Note that for any space X each of these topological spaces is a subspace of Set(X). We obtain the following chain of spaces:

$$\exp^{ccon}(X) \subseteq \exp^{con}(X) \subseteq \exp(X) \subseteq Set(X)$$
(3)  
$$\exp^{c}(X) \subseteq \exp X$$
(4)

**Definition** [2]. A non-empty space X is called k-connected  $(0 \le k \le \infty)$  (denoted by  $X \in C^r$ ) if every continuous mapping  $f: S^r \to X$  with  $r \le k$  is homotopic to a constant mapping  $f: S^r \to \{x_0\}$  where  $x_0 \in X$ .

This definition is equivalent to the following:

If any mapping  $f: S^r \to X$  can be extended to a continuous mapping  $f: D^{r+1} \to X$ , where  $BdD^{r+1} = S^r$ ,  $D^{r+1}$  is closed,  $BdD^{r+1}$  – denotes the boundary  $D^{r+1}$ .

Recall that a space X is called locally k-connected (denoted by  $X \in LC^n$ ) if it is locally k-connected for k = 0, 1, ..., n, i.e. if, for any point  $y_0 \in X$  and any of its neighborhoods V, there exists another neighborhood  $V_0$  of it contained in V and such that any mapping  $f: S^k \to V_0$ , where  $k \leq n$ , is homotopic to a constant mapping  $f: S^k \to V$ .

It is easy to see that a (local) 0 – connection is simply a (Local) path connection. For k = 1, our definition is equivalent to the standard definition of (local) simply connected.

We also recall that  $X \in C$  (respectively,  $X \in LC$ ) means the contractibility (respectively, local contractibility) of the space X.

- a.  $C \Longrightarrow C^{\infty} \Longrightarrow C^n$ , where n = 0, 1, 2, ...
- b.  $LC \Longrightarrow LC^{\infty} \Longrightarrow LC^{n}$ , where n = 0, 1, 2, ...
- c.  $C^n \Longrightarrow C^m$  for  $n \ge m$ .
- d.  $LC^n \Longrightarrow LC^m$  for  $n \ge m$ .

Recall that a space X is called linear-connected if for any two points  $x_0, x_1 \in X$  there is a path connecting them in X. A space X is called contractible if the identity mapping  $id_X : X \to X$  is homotopic to the constant mapping  $const_{x_0} : X \to x_0$  that takes all X to the point  $x_0 \in X$ .

Membership of  $X \in C^k$  is equivalent to the following:

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For any simplex T of dimension  $\geq 1$ , any continuous map has a continuous extension  $F:T \to X$  such that any base set O of the space X containing f(A) also contains F(T), where A is the union of an arbitrary set of faces of the simplex T of dimension  $\geq 1$ , including all one-dimensional.

Now we need an  $\ell_2$  Hilbert space, the points of this space are all possible sequences of  $x = \{x_k : k \in N\}$  real numbers satisfying the  $\sum_{k=1}^{\infty} x_k^2 < \infty$  condition; and the norm (metric) of an element  $x \in \ell_2$  is given by the formula

$$\|x\| = \left(\sum_{k=1}^{\infty} x_k^2\right)^{\frac{1}{2}}$$
(5)

The following takes place

**Theorem [3].** The Hilbert space  $\ell_2$  considered as a topological space is homomorphic to a countable infinite power  $R^{\omega}$  of the real line.

An *n*-dimensional Euclidean space  $\mathbb{R}^n$  can be defined as the subspace of a Hilbert space consisting of those points  $x = \{x_k : k \in N\}$  from  $\ell_2$  for which  $x_k = 0$  for all k > n.

A system of points  $x^i = \{x_k^i\}, i = 0, 1, 2, ..., m$ , from  $\ell_2$  is called independent if their linear combination,  $\mu_0 x^0 + \mu_1 x^0 + ... + \mu_m x^m$ , where  $\mu_0 + \mu_1 + ... + \mu_m = 0$  is equal to zero, only when all  $\mu_i = 0$ .

If the system of points  $x^i, i = 0, 1, ..., m$  is independent, then the collection of points  $x \in \ell_2$ representable in the form  $x = t_0 x^0 + t_1 x^1 + ... + t_m x^m$ , where  $t_i \ge 0$  and  $t_0 + t_1 + ... + t_m = 1$  is called a (closed) *m*-dimensional simplex with vertices  $x^0, x^1, x^2, ..., x^m$  is denoted by  $T(x^0, x^1, x^2, ..., x^m)$  the coefficients  $t_0, t_1, t_2, ..., t_m$  uniquely determined by the point *x* and uniquely determining this point are called its barycentric, (in a barycentric coordinate system consisting of points  $x^0, x^1, x^2, ..., x^m$ ). If a *T*-(closed) *m*-dimensional simplex with vertices  $x^0, x^1, x^2, ..., x^m$ , then the set of all points  $x \in T$ , all barycentric coordinates of which in the system  $x^0, x^1, x^2, ..., x^m$ are positive, is called an open *m*-dimensional simplex (with the same vertices as *T*) and denoted by < T >. The difference  $T \setminus < T >= bdT$  is called the boundary of the simplex *T*. By the face of the simplex T we mean the simplex T, all of whose vertices are the vertices of a given simplex T. A set (lying in a Hilbert space) represented as a finite (or locally finite) union of simplices is called a polyhedron. The union of all at most k-dimensional simplices of the polyhedron P is called its k-dimensional skeleton and is denoted by  $P^{(k)}$ . In particular, the zero-dimensional skeleton  $P^{(0)}$  of the polyhedron P coincides with the set of all its vertices [3-7].

**Definition [3].** A mapping  $p: X \to Y$  is said to be locally soft if, for any separable metrizable space B, any of its closed subspaces A, and any two mappings  $\alpha: A \to X$  and  $\rho: B \to Y$  such that  $p_{\alpha} = p|_A$  there is a mapping  $\gamma: U \to X$  defined on some open neighborhood U of the set A in B such that  $\gamma/_A = \alpha$  and  $p\gamma = \rho/u$ , those, there is a diagram

$$X \xrightarrow{p} Y$$

$$\alpha \uparrow \Box^{\gamma} \uparrow \rho$$

$$A \subset U \subset B$$

$$X \xrightarrow{p} Y$$

$$\alpha \uparrow \Box^{\gamma} \uparrow \rho$$

$$A \subset B$$
(6)
(7)

If, under the indicated conditions, the neighborhood U can always be assumed to coincide with the entire space B, then the mapping P will be called soft.

Let us agree to say that a space (recall that we consider only separable metrizable spaces) is an absolute (neighborhood) extensor if the constant mapping of this space is a (locally) soft mapping. The class of all absolute (neighborhood) extensors is denoted by A(N)E.

The definition of the functor Set(X) and the structure of its open sets, as well as the continuity of open mappings, imply the following [8-10]:

**Theorem [9].** Let  $f: X \to Y$  be a continuous open mapping between topological spaces X and Y. Then the mapping  $\operatorname{Set}(f): \operatorname{Set}(X) \to \operatorname{Set}(Y)$  is also open.

We say that a category K is given if a class of objects O and a class of morphisms Mor(A, B) elements, category K, are given, and

- For every pair of objects (A, B) from K, a set Mor(A, B) is given, called a morphism A into B;
- 2. For each triple of objects (A, B, C) from K, a mapping is given

 $\mu: Mor(A, B) \times Mor(B, C) \rightarrow Mor(A, C)$  ( $\mu(u, v)$  image of a pair

 $(u,v) \in Mor(A,B) \times Mor(B,C)$  is denoted by  $v \cdot u$  and is called the composition of the morphisms u and v;

- 3. The sets Mor(A, B) and the composition of morphisms satisfy the following axioms:
- a. The composition is associative, i.e. for each triple of morphisms  $u, v, \omega$ , the equality  $\omega \cdot (u \cdot v) = (\omega \cdot u) \cdot v$  holds;
- b. For each object A from K there is a morphism 1<sub>A</sub>: A→A, called the identity morphism of the object A, such 1<sub>A</sub> · u = u and v · 1<sub>A</sub> = v for any morphisms u ∈ Mor(B,A) and v ∈ Mor(A,B);
- c. all pairs (A, B) and (A', B') are different, then the intersection of the sets Mor(A, B) and Mor(A', B') is empty.

An important example of a category is the category TOP of all topological spaces and their continuous mappings. The set Mor(X,Y) for any two topological spaces is in this case the simple set of all continuous mappings from X to Y. Composition is understood as the usual composition of mappings.

Quite similarly, a category is also formed by collections of different topological spaces with an appropriate choice of the properties characterizing them. For example, a category is the class of all compact spaces and their continuous mappings into themselves, etc. [11-16].

## **Example.** Category $TOP_{\gamma}$ .

Another example of a category is the category  $TOP_Y$ . Objects of this category are continuous mappings into a given topological space Y. The morphism connecting for an object  $f_1: X_1 \to Y$ and  $f_2: X_2 \to Y$  is a mapping  $g: X_1 \to X_2$  such that  $f_2g = f_1$ . To be extremely precise, the morphism is a triangular commutative diagram

Identity mapping of object  $f: X \to Y$  is identity mapping  $id_X$ .

The product of a family of objects in a category  $TOP_Y$  is defined as follows: Let a family of mappings  $f_\alpha : X_\alpha \to Y$ ,  $\alpha \in A$  be given. In a topological product  $Y^A = \prod \{Y_\alpha : \alpha \in A\}$ , where  $Y_\alpha = Y$ , for each  $\alpha \in A$ , consider the diagonal

$$\Delta(Y^A) = \{ \{ y_{\alpha} : \alpha \in A \} \in Y^A : y_{\alpha} = y_{\beta}, \forall \alpha, \beta \in A \}.$$

We denote by X the complete preimage of the diagonal  $\Delta(Y^A)$  with respect to the mapping  $\prod\{Y_{\alpha}: \alpha \in A\}$ , and by  $f_A$  the restriction of this mapping to the set X. The natural homeomorphism of the diagonal  $\Delta(Y^A)$  onto the space Y is denoted by  $\delta_A$ . We denote the composition  $\delta_A f_A$  by f. The space X will be called the fan product of the spaces  $X_{\alpha}$  with respect to the mappings  $f_{\alpha}$ . If Y is one-point, then the fan product, as is easy to see, coincides with the usual one. The mappings f are called the fibrewise product of the mappings  $f_{\alpha}$ . It can be verified that the fibrous product f of the mappings  $f_{\alpha}$  is the product of objects  $f_{\alpha}$  in the category  $TOP_Y$ . Let us also agree to denote by  $\varphi_{\alpha}$  the restrictions of the projections  $\pi_{\alpha}: \Pi\{X_{\alpha}: \alpha:\in A\} \to X_{\alpha}$  on X and call them projections of the fan product. It is easy to see that the equality  $f = f_{\alpha}\varphi_{\alpha}$  holds for any  $\alpha \in A$ .

Each topological space can be identified with its mapping into some fixed one-point space and, therefore, the category TOP is a subcategory of the category  $TOP_{Y}$ .

Let  $\mathcal{G} = (V, \mathsf{M})$  and  $\mathcal{G}' = (V', \mathsf{M})$  be two categories. A mapping  $\mathcal{F} : \mathcal{G} \to \mathcal{G}'$  that transforms objects into objects and morphisms into morphisms is called a covariant (contravariant) functor from category  $\mathcal{G}$  to category  $\mathcal{G}'$  if:

- 1) for any morphism  $f: X \to Y$  from the category  $\mathcal{G}$ , the morphism  $\mathcal{F}(f)$  acts from  $\mathcal{F}(X)$ to  $\mathcal{F}(Y)$  (from  $\mathcal{F}(X)$  to  $\mathcal{F}(Y)$ );
- 2)  $\mathscr{F}(id_X) = id_{\mathscr{F}(X)}$  for every  $X \in V$ ;
- 3)  $\mathscr{F}(f \circ g) = \mathscr{F}(f) \circ \mathscr{F}(g) \ (\mathscr{F}(g) \circ \mathscr{F}(f));$

Let  $\mathscr{F}_i : \mathscr{G} \to \mathscr{G}'$ ,  $i = \overline{1,2}$  be two covariant functors from a category  $\mathscr{G} = (V, \mathsf{M})$  to a category  $\mathscr{G}' = (V', \mathsf{M})$ . A family of morphisms  $\Phi = \{f_X : \mathscr{F}_1(X) \to \mathscr{F}_2(X), x \in V\} \subset V'$  is

called a natural transformation of a functor  $\mathscr{F}_1$  into a functor  $\mathscr{F}_2$  if, for every morphism  $f: X \to Y$  of a category  $\mathscr{G}$ , the diagram

$$\begin{aligned}
\mathcal{F}_{1}(X) &\xrightarrow{f_{X}} \mathcal{F}_{2}(X) \\
\mathcal{F}_{1}(f) &\downarrow \qquad \qquad \downarrow \mathcal{F}_{2}(X) \\
\mathcal{F}_{1}(Y) &\xrightarrow{f_{Y}} \mathcal{F}_{1}(Y)
\end{aligned} \tag{9}$$

Let  $\mathscr{F}_1, \mathscr{F}_2$  be functors acting from the category V into itself. A functor  $\mathscr{F}_1$  is called a subfunctor (overfunctor) of the function  $\mathscr{F}_2$  if there exists a natural transformation  $\Phi = \{f_X\}: \mathscr{F}_1 \to \mathscr{F}_2$  such that every mapping  $f_X$  is an embedding (epimorphism). In the second case, the functor  $\mathscr{F}_2$  is called the functor-functors of the functor  $\mathscr{F}_1$ .

Note that the essential functor Id and the functors  $\exp$ ,  $\exp^{c}$ ,  $\exp^{ccon}$  are covariant subfunctors of the functor Set on the category of *Top*-topological spaces and continuous mappings into itself. The definition of a covariant functor and the definition of morphisms Set(f) on the category *Top* of topological spaces and continuous mappings into itself imply the following.

**Theorem 1.** a) The functor **Set** is a covariant functor in the category *Top*;

b) The functor Set:  $Top \to Top$  preserves the layers of a continuous mapping, that is,  $(Set(f))^{-1}(f(A)) = Set(f^{-1}(A)).$ 

Let X be an infinite topological  $T_1$ -space. We denote by  $\operatorname{Set}_{\chi_0}(X)$  the family of all finite and countable subsets of the space X, that is,

Set<sub>$$\chi_0$$</sub> $(X) = \{F : F \subseteq X; |F| \le \chi_0\};$   
 $\exp_n(X) = \{F : F \subseteq X; |F| \le n\};$   
 $\exp_\omega(X) = \bigcup_{n=1}^{\infty} \exp_n(X);$ 

from here

$$\exp_{\omega}(X) \subseteq \operatorname{Set}_{\chi_0}(X), \operatorname{Set}_{\chi_0}(X) \subseteq \operatorname{Set}(X).$$

For any map  $f: X \to Y$ , the fiberwise exponent  $\overline{f}_f: X \to Y_1$  where  $X_f = \{F \in \operatorname{Set}(X): F \subset f^{-1}(y), y \in Y\}$  is defined, so that  $\overline{f}(F) = y$  if  $F \subset f^{-1}(y)$ .

Consider the commutative diagram

$$Z_{0} \xrightarrow{g} X$$

$$\downarrow {}^{k} \Box \qquad \downarrow f$$

$$Z \xrightarrow{n} Y$$
(10)

where  $Z_0$  is a closed subset of the compact set.

(\*): The problem of the existence of an extension  $k: Z \to X$  of a mapping g such that  $f \circ k = h$ .

The mapping f is called n-soft, n = 0, 1, 2, ... if problem (\*) has a solution whenever dim  $\subseteq n$ ;  $\infty$ -soft mappings are simply called soft mappings.

A subset A (not necessarily closed) of a space X is called C-embedded if every continuous function  $f: A \to R$  (respectively,  $f: A \to I = [0,1]$ ) is continuous to all X.

A space Y is called contractible (for short,  $Y \in C$ ) if there exists a homotopy  $H(y,t): Y \times I \to Y$  such that  $H(y,0) = id_y$  and H(y,1) are trivially locally contractible (for short,  $Y \in LC$ ) if any point  $y \in Y$  and any of its neighborhoods U has a smallest neighborhood  $V \subseteq U$  such that the written embedding is homotopy trivially.

**Theorem 2.** The functor **Set** preserves the contractibility of topological spaces.

**Proof.** Let X be a contractible space and  $H(x,t): X \times [0,1] \to X$  a homotopy connecting the mappings  $H(x,1) = id_X = h_0$  and  $H(x,1) = 1_{x_0} = h_1$ . An embedding  $i_t: X \times \{t\} \to X \times I$  for each  $t \in [0,1]$  defines an embedding  $Set(i_t): Set(X \times \{t\}) \to Set(X \times [0,1])$ . But the space  $Set(X \times \{t\})$  is naturally homeomorphic to the space  $Set(X \times \{t\})$ . Therefore, a natural embedding  $Set(X) \times I \to Set(X \times [0,1])$  is defined. Then the restriction  $Set(H(x,t))|_{Set(X) \times I}$  of the mapping Set(H(x,t)) is a continuous homotopy connecting the mappings  $Set(h_0)$  and  $Set(h_1)$ , that is, it is the desired homotopy. Hence the space Set(X) is contractible. Theorem 2 is proved.

If X is nested in Y, then Set(X) is also nested in Set(Y).

A set A of a space X is called a retract X if there exists a continuous mapping  $r: X \to A$ such that r(a) = a is true for any  $a \in A$ , that is, there exists a continuous map of the space X onto the subspace A leaving the points of the set A fixed.

**Proposition [5].** A subspace A is a retract of the space X if and only if, for any space Y, each map  $g: A \to Y$  admits an extension to the space X.

If a set A is everywhere dense in X, then Set(A) is also everywhere dense in Set(X).

Question: if X is a  $T_i$  space, then Set(X) is also a  $T_i$  space?

Let X be a topological  $T_1$  – space

 $\operatorname{Set}(X) \cdot i_X(X) \subset \operatorname{Set}(X), \quad i_X(X) \quad C - \text{nested, in } \operatorname{Set}(X), \text{ i.e. } f : i_X(X) \to R \text{ is}$ continuous,  $\exists f : \operatorname{Set}(X) \to R$  that  $f \mid_{i_X(X)} = f$ .

$$O(u_1, u_2, \dots, u_k) = \{A : A \in \operatorname{Set}(X), A \subset \bigcup_{i=1}^k u_i, A \cap u_i \neq \emptyset, i = \overline{1, k}\} \text{ are the basic sets of}$$

the space Set(X). Now we consider the complement of the basic set in the space Set(X), that is, which sets are closed sets in Set(X).

On the other hand:

$$O(u_{1}, u_{2}, ..., u_{k}) = \{A : A \in \operatorname{Set}(X), A \subset \bigcup_{i=1}^{k} u_{i}\} \cap (\bigcap_{i=1}^{k} \{A : A \in \operatorname{Set}(X), A \cap u_{i} \neq \emptyset\})$$
(11)  

$$\operatorname{Set}(X) \setminus O(u_{1}, u_{2}, ..., u_{k}) = (\operatorname{Set}X \setminus \{A : A \in \operatorname{Set}(X); A \subset \bigcup_{i=1}^{k} u_{i}\}) \cup$$
  

$$\bigcup (\operatorname{Set}X \setminus \bigcap_{i=1}^{k} \{A : A \in \operatorname{Set}X, A \cap u_{i} \neq \emptyset\}) = \operatorname{Set}X \setminus \{A : A \in \operatorname{Set}X, A \subset \bigcup_{i=1}^{k} u_{i}\} \cup$$
  

$$\bigcup (\bigcup_{i=1}^{k} \operatorname{Set}(X) \setminus \{A : A \in \operatorname{Set}X, A \cap u_{i} \neq \emptyset\}).$$
(12)

Hence, this set consists of the union of the following sets:

a. Set 
$$X \setminus \{A : A \in \text{Set} X : A \subset \bigcup_{i=1}^{k} u_i\};$$
 (13)

b. Set  $X \setminus \{A : A \in \text{Set} X : A \cap u_i \neq \emptyset\};$ 

Now, if we expand, we get

$$\operatorname{Set} X \setminus \{A : A \in \operatorname{Set} X, A \subset \bigcup_{i=1}^{k} u_i\} = \{A : A \in \operatorname{Set} X, A \subset X \setminus \bigcup_{i=1}^{k} u_i = \bigcap_{i=1}^{k} (X \setminus u_i)\}$$
(14)

 $\operatorname{Set} X \setminus \{A : A \in \operatorname{Set} X, A \cap u_i \neq \emptyset\} = \{A : A \in \operatorname{Set} X, A \cap u_i \neq \emptyset\} = \{A : A \in \operatorname{Set} X, A \subset X \setminus u_i\}$ 

It turns out that if  $u_1, u_2, ..., u_k$  are open, then the sets

$$\{A : A \in \operatorname{Set} X, A \subset \bigcup_{i=1}^{k} u_i\} = \operatorname{Set}(\bigcup_{i=1}^{k} u_i, X),$$

$$\{A : A \in \operatorname{Set} X, A \cap u_i \neq \emptyset\} = \operatorname{Set} X \setminus \operatorname{Set}(X \setminus u, X)$$
(15)

are open in the space of nonempty subsets by the definition of the exponential set Set(X).

On the other hand, the elements of the prebase that we specified when defining the exponential topology have this form:

$$\operatorname{Set}(u, X) = O(u), \operatorname{Set}(X) \setminus \operatorname{Set}(X \setminus u, X) = O(u, X).$$

Thus, the families of all sets of the form  $O < u_1, u_2, ..., u_k >$ , where the sets  $u_1, u_2, ..., u_k$  are open in the space X, are the base of the exponential topology in the space Set(X).

**Condition** [1].  $LC^{\#}$ : There is a base of neighborhoods satisfying Condition  $C^{\#}$ .

**Theorem [1].** If a topological space Z has the property  $LC^{\#}$ , then for any of its open coverings  $\gamma$  there is an open cover  $\omega$  of it such that for every polytope  $P_C$  by the Whitehead topology every  $\omega$ -realization of  $f: A \to Z$  (where an A-subpolytop containing all edges from P) has extensions  $ext: P \to \Box$ , which is a  $\gamma$ -implementation.

**Condition**.  $C^{\#}$ : For any simplex T of dimension  $\geq 1$ , any continuous mapping has a continuous extension  $F:T \to Z$  such that any base set  $O_{\tau}$  of the space Z containing f(A) contains F(T).

Condition equivalent to  $C^{\#}$ : Any continuous mapping  $f: S^n \to Z, n \ge 1$ , has a continuous extension  $F: Q^{n+1} \to Z$  to the ball bounded by the sphere  $S^n$  such that if  $f(S^n) \subset O_{\tau}$ , then  $f(Q^{n+1}) \subset O_{\tau}$ .

For a topological space X, here  $\Box$  denotes one of the following spaces: *SetX*, *Comp*, *ConnX*, *ContX* for arbitrary X, and  $\exp X$ ,  $\exp X \cap ConpX$ ,  $\exp X \cap ConnX$ ,  $\exp X \cap ContX$  (for regular X) where  $\exp X$  is the family of all non-empty closed subsets, Set X is the family of all non-empty subsets, CompX -family of all non-empty compact subsets, ConnX -family of all non-empty connected subsets, ContX -family of all non-empty connected compact subsets of X [17].

**Proposition.** The functor *Set* preserves retractions.

**Proof.** Let X be a topological space  $A \subset X$  and  $r: X \to A$  a continuous retraction. Then

The mapping  $Set(r): Set(X) \rightarrow Set(A)$  is also continuous [1]. It is known that  $Set(A) \subset Set(X)$  and the retraction  $r: X \rightarrow A$  leave the points of the subspace A movable. Consequently, under the mapping Set(r), the points of the space Set(A) remain fixed, since the functor *Set* preserves points and empty sets. Hence, Set(r) is a retraction, i.e. Set(A) is a retract of Set(X). The proposition is proved.

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